

# 2 MODULAR DIGITS WITH SERIAL INTERFACE



The K8063 is a 7-segment display which can be controlled by a two-wire serial connection, using the RS232 protocol. The protocol is platform-independent i.e. any computer running any programming language can control the K8063, as long as it is equipped with a serial port. Up to 255 units can be individually addressed, allowing you to create large display systems for e.g. scoreboards, clocks, timers, thermometers, games, ...

### Features

- ☑ Red bright 57mm jumbo 7-segment display
- ☑ Complete with snap-in enclosure
- Multiple units can easily be linked in order to create larger readouts for different purposes e.g. scorekeeping, timing, counting, ...
- ☑ Easy platform-independent control via three-wire RS232 interface
- ☑ Up to 255 separate units can be addressed
- ☑ Tested with distances of up to 50m between PC and display
- ☑ Use our optional PCUSB6 for USB connection

### Specifications

- Power supply: 9 to 12Vdc / 120mA per display
- RS232 interface: 2400baud / 8databits / no parity / 1 stop bit
- Dimensions: 74 x 58.5 x 32mm

The general manuals containing guidelines for assembly, safety and electromagnetic compatibility can be downloaded from our Velleman website (support / manuals / HALG).

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#### 1. Assembly (Skipping this can lead to troubles !)

Ok, so we have your attention. These hints will help you to make this project successful. Read them carefully.

#### 1.1 Make sure you have the right tools:

- A good quality soldering iron (25-40W) with a small tip.
- Wipe it often on a wet sponge or cloth, to keep it clean; then apply solder to the tip, to give it a wet look. This is called 'thinning' and will protect the tip, and enables you to make good connections. When solder rolls off the tip, it needs cleaning.
- Thin raisin-core solder. Do not use any flux or grease.
- A diagonal cutter to trim excess wires. To avoid injury when cutting excess leads, hold the lead so they
  cannot fly towards the eyes.
- Needle nose pliers, for bending leads, or to hold components in place.
- Small blade and Phillips screwdrivers. A basic range is fine.

For some projects, a basic multi-meter is required, or might be handy

### 1.2 Assembly Hints :

- $\Rightarrow$  Make sure the skill level matches your experience, to avoid disappointments.
- ⇒ Follow the instructions carefully. Read and understand the entire step before you perform each operation.
- ⇒ Perform the assembly in the correct order as stated in this manual
- ⇒ Position all parts on the PCB (Printed Circuit Board) as shown on the drawings.
- $\Rightarrow$  Values on the circuit diagram are subject to changes.
- ⇒ Values in this assembly guide are correct\*
- $\Rightarrow$  Use the check-boxes to mark your progress.
- $\Rightarrow$  Please read the included information on safety and customer service

\* Typographical inaccuracies excluded. Always look for possible last minute manual updates, indicated as 'NOTE' on a separate leaflet.



Assembly hints

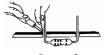
### 1.3 Soldering Hints :

- 1- Mount the component against the PCB surface and carefully solder the leads
- 2- Make sure the solder joints are cone-shaped and shiny
- 3- Trim excess leads as close as possible to the solder joint

**REMOVE THEM FROM THE TAPE ONE AT A TIME !** 

AXIAL COMPONENTS ARE TAPED IN THE CORRECT MOUNTING SEQUENCE !

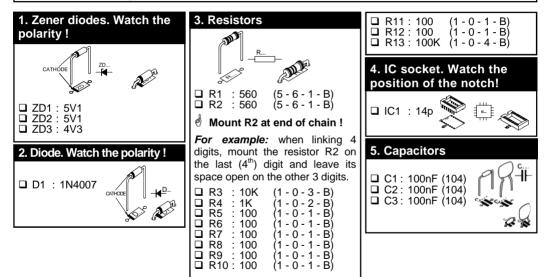


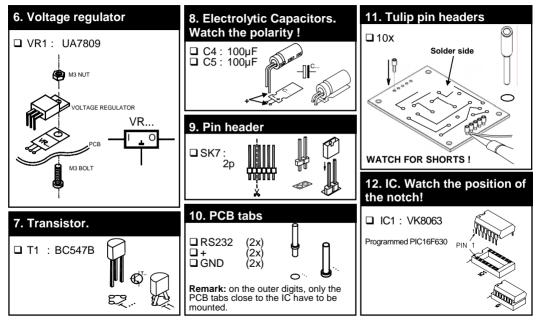




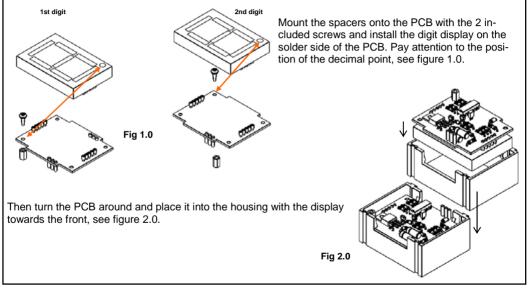


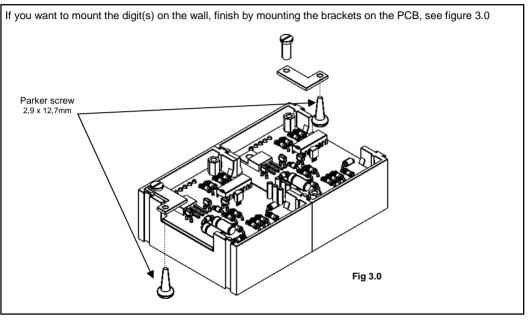
**Remark:** all components are supplied in a double quantity to allow the assembly of 2 digits. Repeat the procedure of the first digit to assemble the second one.



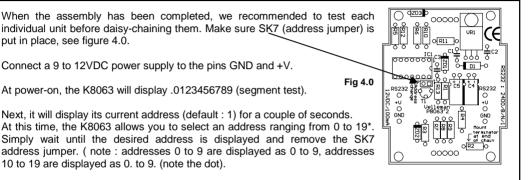


# 13. Assembly





# 14. Test



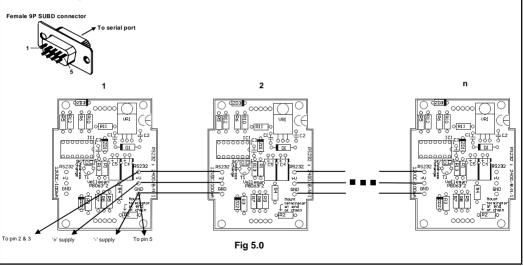
The K8063 will loop the addresses until the jumper is removed, so if you have missed the desired address, you can wait a while and it will appear again.

Once you have removed the jumper, the K8063 stops looping and after a couple of seconds the display will turn blank. The selected address is now stored in its memory.

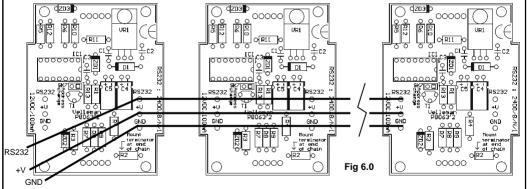
\*If you require 20 or more different addresses, you can configure them when the K8063 units are hooked-up to the computer (see further in this manual).

# 15. Hook-up

**Hook-up** : All units have two sets of connectors. This allows you to hook them up in an easy way, as shown below (fig. 5.0):



**Power supply :** The K8063 requires a 9 to 12VDC power supply. Power consumption is 120mA max. per unit (12V) (e.g. if you have 5 units, you need a power supply capable of delivering at least 5x120 = 600mA). Note : If the total # of displays exceeds 6, it is required to wire the units according to the drawing below, as the PCB tracks are unable to handle the large currents that flow when more than 6 units are operated simultaneously. Furthermore, if more than 15 units are operated at the same time, we recommend to use a separate power supply for every group of 15 digits, to avoid large currents and to avoid the need for heavy wiring. (Fig 6.0).



Serial port specifications : The K8063 can be hooked up to any serial port which supports the RS232 standard (e.g. PC COM port). Serial port settings are 2400/8/n/1 (2400 baud, 8 databits, no parity, 1 stopbit).

**Serial port connection :** Connect the pin marked 'RS232' to pins 2&3 of the 9P SUBD connector. Connect the pin marked 'GND' to pin 5 of the 9P SUBD connector. We have successfully bridged up to 50m between the serial port and the last digit, using standard UTP (twisted pair) cable. Make sure to remove resistor R2 (terminator) from all K8063 units **except** the last unit (unit n in the example above).

### Controlling one or more K8063 via a computer:

In order to display information on the K8063, you need to send it a correct data string. The data string consists of 5 bytes :

Byte 1 : chr\$(13) (letting the K8063 know that data will come in)

*Byte 2* : address (0 to 255) (determines the individual K8063 you want to access. Note: Address '0' accesses all connected K8063)

*Byte3* : command (A # of commands are available, to control the various functions of the K8063, see list of commands)

*Byte4* : parameter (Most commands require a parameter. See list of commands)

Byte5 : checksum Two-compliment of the sum of the previous 4 bytes 256 - (Byte1+ Byte2 + Byte3 + Byte4) MOD 256

### Available commands:

Command	Description	Parameter
'E'	Emergency stop	Don't care (anything goes)
'D'	Display address on all digits	Don't care
'B'	Byte-command	0255 (see drawing)
'S'	Strobe command	Don't care
'C'	Change address	0255 (new address)
'R'	Reset all displays	Don't care
' <b>F</b> '	Force address	Don't care
' <b>A</b> '	Send ASCII	32,4857 (blank, 09)
'P'	Decimal <b>p</b> oint	0 or 255 (OFF / ON)
ʻl'	Intensity control	0 or 255 (BRIGHT / DIM)

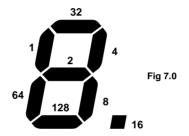
# **'E'**: Emergency stop. All displays are blanked, regardless of address. (Hint : execute the 'Strobe' command to restore all displays)

 $^{\prime}\text{D}^{\prime}$  : Display address all digits. All digits show their address. Addresses between 0 and 9 are displayed as 0 to 9

Addresses between 10 and 19 are displayed as 0. to 9. (See earlier). Addresses between 20 and 255 are displayed in a binary fashion (see drawing).

Hook-up

**'B'**: Allows you to turn on individual segments. Parameter = sum of the values of the individual segments (see drawing 7.0) (e.g. 7 = 32+4+8= 44).



**'S'**: Strobe command. After executing a 'B', 'A' or 'P' –command, the displays are not updated, you need to execute the 'S'-command. By doing this, all displays are updated at the same time.

**'C'**: Change address. Allows you to change the address of an individual K8063. Put jumper SK7 in place on each K8063 which needs to respond to the 'change address'-command. When the command has been executed, the new address is displayed. Remove the jumper(s).

'R': In the unlikely event of strange behavior of one or more displays, you can reset all displays at once by executing this command.

**'F':** Force all displays to address '1' (return to factory settings).

'A': Send ASCII to display. An easy way of displaying figures 0 to 9
 Simply send their ASCII value. (32ascii blanks the display, 0 = 48ascii, 9 = 57ascii).

'P': Decimal point control. Parameter 255 turns the decimal point on, parameter 0 turns it off. Decimal point remains on until it has been forced off.

I': Brightness control. Parameter 255 set the display to 'dim', parameter 0 sets the display to 'bright'.

**Remark :** For best results, we recommend to send the command string at least three times a row. When the brightness is set to dim, it is recommended to send the string at least 4 times to make sure all displays are updated.

Furthermore, we recommend a delay of at least 100ms between sending a command and sending the 'Strobe'-command.

### Command string examples :

EX1: To reset all displays : Execute the 'R'-command

Data to be sent to serial port :

- Chr\$(13) (Init command)
- Chr\$(8) (Don't care)
- Chr\$(82) "R" = Reset command
- Chr\$(1) (Don't care)

Chr\$(152) (Checksum : 2-compliment of the sum of the 4 previous bytes)

**EX2:** To display a '0' on all units with address '1': Execute the 'A'-command and supply address '1'. Next, execute the 'S' (strobe) command.

Data to be sent to serial port :

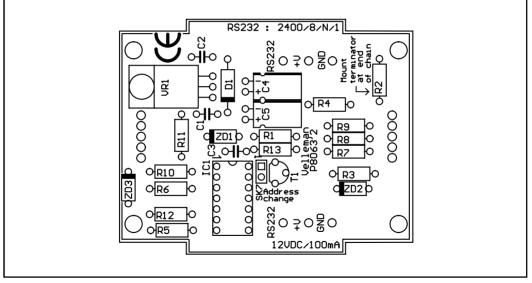
Chr\$(13)	(Init command)
Chr\$(1)	(Address 1)
Chr\$(65)	"A" = ASCII command
Chr\$(48)	(ASCII value of zero = 48)
Chr\$(129)	(Checksum : 2-compliment of the sum of the 4 previous bytes)
100ms pause	
Chr\$(13)	(Init command)
Chr\$(8)	(Don't care)
Chr\$(83)	"S" = strobe command
Chr\$(1)	(Don't care)
Chr\$(151)	(Checksum : 2-compliment of the sum of the 4 previous bytes)

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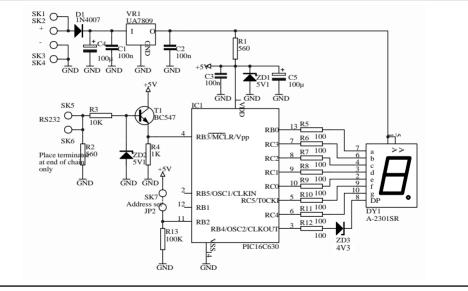
<b>EX3:</b> To turn on all segments on all units with address '1' : Execute the 'B'-command and supply address '1'. Next, execute the 'S' (strobe) command.		
Data to be sent to serial port :		
Chr\$(13)	(Init command)	
Chr\$(1)	(Address 1)	
Chr\$(66)	"B" = Byte command	
Chr\$(255)	(255 = sum of segments)	
Chr\$(177)	(Checksum : 2-compliment of the sum of the 4 previous bytes)	
100ms pause		
Chr\$(13)	(Init command)	
Chr\$(8)	(Don't care)	
Chr\$(83)	"S" = strobe command	
Chr\$(1)	(Don't care)	
Chr\$(151)	(Checksum : 2-compliment of the sum of the 4 previous bytes)	
Note : Our website <u>www.velleman.be</u> features some example programs written in VB6 which can be used as a guide for writing your own software (source code is supplied).		



# 16. PCB



# 17. Diagram





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